

# **SPECIFICATION**

## **Electric Valve Actuators in Power Plants**

All electric actuators shall be suitable for installation in electric power generating stations.

Actuators shall contain motor, gearing, manual over-ride, limit switches, torque switches, drive coupling, integral motor controls, position feedback transmitter (where required) and mechanical dial position indicator (where required).

The motor shall be specifically designed for actuator service. The motor will be of the induction type with class F insulation and protected by means of thermal switches imbedded in the motor windings. Motor enclosure will be totally enclosed, non-ventilated.

Motors will be capable of operating on 460 volt - 3 phase- 60 hertz power.

Actuator enclosure shall be NEMA 4 (watertight) and suitable for short term submersion in water to a depth of 6 feet for 30 minutes.

All external fasteners on the electric actuator will be stainless steel. Fasteners on limit switch and terminal compartments shall be captured to prevent loss while covers are removed.

All gearing shall be grease lubricated and designed to withstand the full stall torque of the motor.

Manual over-ride shall be by handwheel. Manual operation will be via power gearing to minimize required rimpull and facilitate easy change-over from motor to manual operation when actuator is under load. Return from manual to electric mode of operation will be automatic upon motor operation. A seized or inoperable motor shall not prevent manual operation.

Limit switches shall be furnished at each end of travel. Limit switch adjustment shall not be altered by manual operation. Limit switch drive shall be by countergear. Limit switches must be capable of quick adjustment requiring no more than five (5) turns of the limit switch adjustment spindle. One set of normally open and one set of normally closed contacts will be furnished at each end of travel where indicated. Contacts shall be of silver and capable of reliably switching low voltage DC source from the control system furnished by others.

Mechanically operated torque switches shall be furnished at each end of travel. Torque switches will trip when the valve load exceeds the torque switch setting. The torque switch adjustment device must be calibrated directly in engineering units of torque.

## **Electric Valve Actuator Specification (continued)**

All wiring shall be terminated at a plug and socket connector.

Quarterturn actuators will be furnished with mechanical stops that restrict the valve/actuator travel.

Actuator must be capable of the following valve closing times/operating speeds: quarterturn valves - 60 second closing time, gate valves - 12 inches per minute operating speed and globe valves - 4 inches per minute operating speed.

Actuators will be capable of operating in an ambient temperature range of -20 to +175 degrees F (without motor controls) and -20 to +160 degrees F (with motor controls).

All actuators in open/close service will be furnished with integral motor controls consisting of reversing starters, control transformer, phase discriminator, monitor relay (to signal fault conditions such as thermal switch trip, torque switch tripped in mid-travel, wrong phase sequence or phase failure), "open-stop-close" pushbuttons, "local-off-remote" selector switch in addition to red and green indicating lights. An interface with the control system must be furnished with optical isolators to separate incoming voltage signals from the internal motor controls.

Actuators in modulating service will be selected such that the required dynamic valve torque is no more than 60% of the electric actuator's maximum rated breakaway torque. Power gearing in modulating actuators shall have zero backlash between the motor and actuator output.

All actuators in modulating service will be furnished with a feedback potentiometer in addition to the following motor controls: reversing starters, control transformer, phase discriminator, monitor relay, positioner, "open-stop-close" pushbuttons, "local-off-remote" selector switch in addition to red and green indicating lights. The positioner shall be capable of accepting a 4-20mADC command signal and positioning the valve by comparing the command signal with the present valve position as indicated by the feedback potentiometer mounted inside the actuator. The positioner shall be field adjustable to fail to the "open", "closed" or "last" position on loss of 4-20mADC command signal.

All actuators shall be manufactured by AUMA Actuators, Inc. of Pittsburgh, Pennsylvania.



